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C. Karen Liu Sumit Jain School Of Interactive Computing  
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Modeling Friction Phenomena In Flexible Multibody Dynamics  
Modeling Friction Phenomena In Flexible Multibody Dynamics\* Olivier A. Bauchau And Changkuan Ju  
Daniel Guggenheim School Of Aerospace Engineering, Georgia Institute Of Technology, 270 Ferst Dr., Atlanta, GA 30332, USA  
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An Underactuated Multi-finger Grasping Device In Figure 1, a A Schematic [1] Of A Five-finger Hand Moved By A Single Actuator Is Shown; The Auto-adaptability Of The Fingers To The Shape Of The Grasped Object Is Obtained By Means Of "sliding Pulleys". In Figure 1b A Study [2] Is Presented, In Cesare Rossi And Sergio Savino:

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Evaluating Pinch Quality Of Underactuated Robotic Hands Then Converted Into Pinch Quality Indicator Using Machine Learning Methods. The Following Sections Talk About The Details Of Sensing, Experiments, Machine Learning Methods And The Optimization. II. DATA ACQUISITION The Basic Experiment Setup Includes An Underactuated Hand Developed For An U Jan 4th, 2024



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