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.. . . Figure 2: Design Of A Splitter. Definition 4.2 An $(f_i; f_l; m; -)$ -splitter is a bipartite graph $G = (V [(W_0 [W_1); E_0 [E_1)$ in which $(V [W_0; E_0)$ and $(V [W_1; E_1)$ represent $(f_i; f_l; m; -)$ -concentrators. Edges in E_0 are called 0-edges, and edges in E_1 are called 1-edges. With the help of the 2th, 2024

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- often Perform Automatic Summarization On Major Network Boundary By Default
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