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Neural-Based Control Of A Robotic HandCarnegie Mellon University, Pittsburgh, Pennsylvania, 15213 Email: Pedram@cmu.edu, Yoky@andrew.cmu.edu Abstract— The Neural-based Control Of A Robotic Hand Has Many Clinical And Engineering Applications. Current Approaches To This Problem Have Been Limited Due To A Lack Of Understanding Of The Relationship Between Neural Signals And 5th, 2024An Adaptive Neural Network Using Model Prediction Control 3 Predictive Control (RT-MPC) Based On Self-organizing Radial Basis Function Neural Network (SORBFNN) Is Proposed For Nonlinear Systems. This RTMPC Has Its Simplicity In Parallelism To Model Predictive Control Design And Efficiency To Deal With Computational Complexity. 3th, 2024Adaptive Battery Control With Neural Networks A State-of-the-art Model Predictive Controller (MPC) Can Adapt To Changes In The System, But Is Limited By Its High Online Computational Requirements. To Better Extract Value At A Reasonable On-line Computational Cost, We

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