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Nonlinear Systems And Control Lecture # 7 Stability Of ...

Theorem: The Equilibrium Point $X = 0$ Of $X' = Ax$ Is Stable If And Only If All

Eigenvalues of A satisfy $\text{Re}[\lambda_i] \leq 0$ and for every eigenvalue with $\text{Re}[\lambda_i] = 0$ and algebraic multiplicity $q_i \geq 2$, $\text{Rank}(A - \lambda_i I) = N - q_i$, where N is the dimension of X . The equilibrium point $X = 0$ is globally asymptotically stable if and only if all eigenvalues of A satisfy $\text{Re}[\lambda_i] < 0$.

Nonlinear Systems And Linearization

When we studied linear systems (the case of two negative eigenvalues). To study the behavior of a nonlinear dynamical system near an equilibrium point, we can linearize the system. We will first explain this approach in general and then return to the example discussed above. Consider a system $\dot{x} = f(x, y)$, $\dot{y} = g(x, y)$. Feb 9th, 2024

Learning-based Lyapunov Analysis For Nonlinear Control Systems

Required system dynamics, which in turn allows us to establish regions of stability. To summarize, the main contributions of this work are as follows: We formulate the searching of safe regions for arbitrary nonlinear dynamical systems as a convex optimization problem, by dealing with a scalar function of states. Apr 8th, 2024

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