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THE LQG/LTR PROCEDURE FOR MULTIVARIABLE FEEDBACK CONTROL ... THE LQG/LTR PROCEDURE FOR MULTIVARIABLE FEEDBACK CONTROL DESIGN* By Gunter Stein** Michael Athans*** ABSTRACT This Paper Provides A New Perspectiv

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X State Step Response X 1 X 2 0 0.5 1 1.5 2 2.5 3 3.5 4 -15 -10 -5 0 5 Time (sec) U Control Step Response: U=Nbar R-Kx U=Nbar R-Kx Figure 3: Response To Step Input With The N⁻ Correction. Gives The Desired Steady- Apr 4th, 2024

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